

**Supplemental notes on chapter 6**  
**Math 129b**

**The Whatever Theorem.** This says:

**The Whatever Theorem.** Let  $V$  and  $W$  be vector spaces, let  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  be a basis for  $V$ , and let  $\mathbf{w}_1, \dots, \mathbf{w}_n$  be vectors in  $W$  (possibly equal to each other or  $\mathbf{0}$ ). Then there exists a unique linear function  $T : V \rightarrow W$  such that  $T(\mathbf{v}_i) = \mathbf{w}_i$  for  $1 \leq i \leq n$ .

The main ideas of the Whatever Theorem are: (1) You can make a linear function do Whatever you want to a basis, and (2) This is essentially the only way to make up a linear function/write down a formula for a linear function.

**The SPAM and One-to-one Lemmas.** These are somewhat complementary tools for proving facts about a linear function  $T$ . The SPAM Lemma can be used to prove  $T$  is onto, or other facts about the image of  $T$ , by finding a SPANning set for the iMage of  $T$ . The One-to-one Lemma deals with the kernel of  $T$ .

**The SPAM Lemma.** If  $T : V \rightarrow W$  is linear and  $\{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  spans  $V$ , then  $\{T(\mathbf{v}_1), \dots, T(\mathbf{v}_n)\}$  spans  $\text{im } T$ .

**The One-to-one Lemma.** If  $T : V \rightarrow W$  is linear, then the following are equivalent:

1.  $T$  is one-to-one.
2.  $\ker T = \{\mathbf{0}\}$ .
3.  $\text{nullity } T = 0$ .

**The matrix of a linear function.** The matrix of the linear function  $T$  relative to the bases  $B$  (domain) and  $B'$  (range) is denoted by  $[T]_{B,B'}$ . Let  $B = \{\mathbf{u}_1, \dots, \mathbf{u}_k\}$ . Then by definition, we have

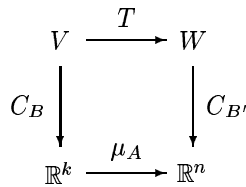
$$[T]_{B,B'} = \left[ [T(\mathbf{u}_1)]_{B'} \cdots [T(\mathbf{u}_k)]_{B'} \right].$$

Slogan: “**The columns tell you where your basis goes.**”

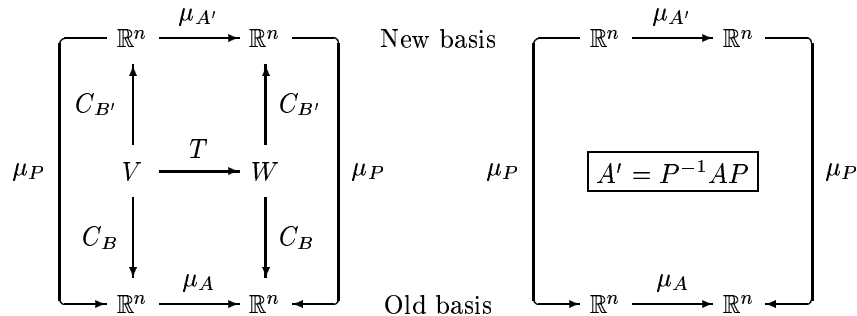
The key property of  $A = [T]_{B,B'}$  is that

$$A(B\text{-coordinates of } \mathbf{v}) = B'\text{-coordinates of } T(\mathbf{v}).$$

Diagram:



**Change of basis.** Suppose  $T : V \rightarrow V$  is linear, and that we know the matrix  $A = [T]_{B,B}$  of  $T$  relative to an old basis  $B$ . Suppose we want to find the matrix of  $T$  relative to some new basis  $B'$ , i.e., suppose we want to find  $A' = [T]_{B',B'}$ . First a diagram of what's going on:



**Definition.** Let  $B = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$  be the old basis, and let  $B' = \{\mathbf{v}'_1, \dots, \mathbf{v}'_n\}$  be the new basis. The *change-of-basis matrix from the basis  $B'$  to the basis  $B$*  is the matrix  $P$  whose  $i$ th column is  $[\mathbf{v}'_i]_B$ :

$$P = \begin{bmatrix} [\mathbf{v}'_1]_B & \cdots & [\mathbf{v}'_n]_B \end{bmatrix}.$$

The key property of  $P$  is that

$$P(B'\text{-coordinates of } \mathbf{v}) = B\text{-coordinates of } \mathbf{v}.$$

Then the formula in the change-of-basis theorem is:

$$[T]_{B',B'} = A' = P^{-1}AP.$$

**The most important case:** Suppose  $V = \mathbb{R}^n$ ,  $T(\mathbf{x}) = A\mathbf{x}$  for all  $\mathbf{x} \in \mathbb{R}^n$ , and the old basis is the standard basis  $S = \{\mathbf{e}_1, \dots, \mathbf{e}_n\}$ . Mercifully, in that case,  $[T]_{S,S} = A$ .

If we want to find the matrix of  $T$  relative to a new basis  $B = \{\mathbf{v}_1, \dots, \mathbf{v}_n\}$ , then  $P$  changes  $B$ -coordinates to  $S$ -coordinates (mnemonic: “change of basis is just a bunch of B.S.”), and the columns of  $P$  are just the vectors in  $B$ .